

Hence, we have Eq. (I.16):

$$i \frac{\partial \phi^{(1)}}{\partial \tau} + p \frac{\partial^2 \phi^{(1)}}{\partial \xi^2} + q |\phi^{(1)}|^2 \phi^{(1)} = 0,$$

with

$$p = m^2/2\omega^3,$$

$$q = -3\kappa/2\omega.$$

For a negative κ , pq is positive so that this equation admits the solitary-wave solution, such as that given by Eq. (I.17), while the plane waves are modulationally unstable as was stated before in Eq. (I.18). On the other hand, if κ is positive, we have the solutions such as those given in Sec. 2 for the plasma wave, and the equation can be reduced to the Kortweg-de Vries equation.

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On Canonical $SO(4, 1)$ Transformations of the Dirac Equation

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Certain matrix transformations of the free-particle Dirac equation are described as momentum-dependent $SO(4, 1)$ transformations. Such of these belonging to any one of five subgroups $G^{(\alpha)}$ ($\alpha = 0, 1, 2, 3, 4$) are canonical, preserving the Lorentz-invariant Dirac scalar product in a corresponding one of five modes of expression. The Dirac equation itself is linear in all five components p_α ($\mu = 0, 1, 2, 3$) is the four-momentum operator, and $p_4 = m$] of the "five-vector" \tilde{p} , and a transformation in $G^{(\beta)}$ has the additional property that the component p_β appears linearly also in the transformed equation. The Mendlowitz and the Foldy-Wouthuysen-Tani transformation accordingly are in $G^{(0)}$, the $SO(4)$ subgroup; and that proposed by Chakrabarti is in $G^{(4)}$, the $SO(3, 1)$ subgroup associated with homogeneous Lorentz transformations. For any \tilde{p}' , obtained from \tilde{p} by a momentum-dependent $SO(4, 1)$ transformation, there is a corresponding transform of the Dirac equation. Where p_α appears in the Dirac equation, p'_α appears in the transformed equation. The ambiguities which arise in the specification of the transformation leading to a given such equation are associated with the existence of a "little group" for any such \tilde{p}' .

1. INTRODUCTION

The Dirac equation for the four-component wavefunction $\psi^{(D)}(x)$ is

$$(\gamma_\mu p^\mu - m)\psi^{(D)} = 0, \tag{1.1}$$

where

$$p_\mu = \frac{i\partial}{\partial x^\mu}, \quad \mu = 0, 1, 2, 3, \tag{1.2}$$

and the matrices γ_μ form an irreducible representation of the Dirac-Clifford algebra, with

$$\{\gamma_\mu, \gamma_\nu\} = 2g_{\mu\nu}. \tag{1.3}$$

[We choose the diagonal metric with $g_{00} = -g_{11} = -g_{22} = -g_{33} = 1$; and, with no significant loss of generality, we take $\gamma_0, i\gamma_1, i\gamma_2, i\gamma_3$, and $i\gamma_5$ ($= i\gamma_0\gamma_1\gamma_2\gamma_3$) to be Hermitian.]

The transformation properties of the bispinor function $\psi^{(D)}(x)$ with respect to the restricted homogeneous Lorentz group $SO(3, 1)$ are well known. However, it has also been long known that larger groups, in fact certain groups of rotations in five- and six-dimensional spaces, are pertinent to discussions of

the Dirac equation, the Lie algebra of the Dirac matrices γ_μ , etc.¹⁻⁷ In this paper, the connection between Eq. (1.1) and the group $SO(4, 1)$ in particular is exploited in the development of a unifying group-theoretical description of certain canonical momentum-dependent transformations of the equation.

In a previous publication,⁸ henceforth referred to as BC, two features of Eq. (1.1) assume significance: namely, the linearity in all five of the quantities p_μ, m , and the existence of five different ways of expressing one and the same Lorentz-invariant scalar product

¹ A. S. Eddington, Proc. Roy. Soc. (London) **121A**, 524 (1928).
² P. A. M. Dirac, Ann. Math. **36**, 657 (1935).
³ Harish-Chandra, Proc. Indian Acad. Sci. **22A**, 30 (1945).
⁴ A. O. Barut, Phys. Rev. **135**, B839 (1964). See also A. J. MacFarlane, Commun. Math. Phys. **2**, 133 (1966); A. ten Kate, J. Math. Phys. **9**, 181 (1968).
⁵ J. K. Lubański, Physica **9**, 310 (1942). See also H. J. Bhabha, Rev. Mod. Phys. **17**, 200 (1945); J. A. de Vos and J. Hilgevoord, Nucl. Phys. **B1**, 494 (1967); M. M. Bakri, J. Math. Phys. **10**, 298 (1969).
⁶ See, for example, C. Fronsdal, Proc. Roy. Soc. (London) **288A**, 113 (1965), and references given therein.
⁷ A. O. Barut, Phys. Rev. Letters **20**, 893 (1968).
⁸ A. J. Bracken and H. A. Cohen, Progr. Theoret. Phys. **41**, 816 (1969).

$(\psi_1^{(D)}, \psi_2^{(D)})$ of any two solutions $\psi_{1,2}^{(D)}(x)$. The five expressions are all simple in the momentum representation, introduced by defining

$$\psi^{(D)}(x_0, \mathbf{x}) = (2\pi)^{-\frac{3}{2}} \int \frac{d^3k}{\omega(\mathbf{k}, m)} e^{i\mathbf{k}\cdot\mathbf{x}} \{ e^{-i\omega(\mathbf{k}, m)x_0} \chi^{(D)+}(\mathbf{k}) + e^{+i\omega(\mathbf{k}, m)x_0} \chi^{(D)-}(\mathbf{k}) \}, \quad (1.4)$$

where

$$\omega(\mathbf{k}, m) = (\mathbf{k}^2 + m^2)^{\frac{1}{2}}, \quad (1.5)$$

and with, conversely,

$$\chi^{(D)\pm}(\mathbf{k}) = e^{\pm i\omega(\mathbf{k}, m)x_0} \frac{1}{2} [\omega(\mathbf{k}, m) \pm p_0] (2\pi)^{-\frac{3}{2}} \times \int d^3x e^{-i\mathbf{k}\cdot\mathbf{x}} \psi^{(D)}(x_0, \mathbf{x}). \quad (1.6)$$

Then the well-known coordinate representation form

$$(\psi_1^{(D)}, \psi_2^{(D)}) = \int_{x_0 \text{ const}} d^3x \psi_1^{(D)\dagger}(x_0, \mathbf{x}) \psi_2^{(D)}(x_0, \mathbf{x}), \quad (1.7)$$

where $\psi^{(D)\dagger}$ is the Hermitian conjugate of $\psi^{(D)}$, yields the five expressions

$$(\psi_1^{(D)}, \psi_2^{(D)}) = \int \frac{d^3k}{\omega^2(\mathbf{k}, m)} \{ \chi_1^{(D)+\dagger}(\mathbf{k}) \chi_2^{(D)+}(\mathbf{k}) + \chi_1^{(D)-\dagger}(\mathbf{k}) \chi_2^{(D)-}(\mathbf{k}) \} \quad (1.8a)$$

$$= \int \frac{d^3k}{m\omega(\mathbf{k}, m)} \{ \bar{\chi}_1^{(D)+}(\mathbf{k}) \chi_2^{(D)+}(\mathbf{k}) - \bar{\chi}_1^{(D)-}(\mathbf{k}) \chi_2^{(D)-}(\mathbf{k}) \} \quad (1.8b)$$

and

$$= \int \frac{d^3k}{\omega(\mathbf{k}, m)k_i} \{ \bar{\chi}_1^{(D)+}(\mathbf{k}) \gamma_i \chi_2^{(D)+}(\mathbf{k}) - \bar{\chi}_1^{(D)-}(\mathbf{k}) \gamma_i \chi_2^{(D)-}(\mathbf{k}) \} \quad (i = 1, 2, \text{ or } 3; \text{ no summation}); \quad (1.8c)$$

where

$$\bar{\chi}^{(D)\pm} = \chi^{(D)\pm\dagger} \gamma_0. \quad (1.9)$$

The equivalence of these five expressions is established using the identity

$$k_\mu \bar{\chi}_1^{(D)\pm}(\mathbf{k}) \chi_2^{(D)\pm}(\mathbf{k}) = m \bar{\chi}_1^{(D)\pm}(\mathbf{k}) \gamma_\mu \chi_2^{(D)\pm}(\mathbf{k}), \quad (1.10)$$

where we define

$$k_0 \chi^{(D)\pm}(\mathbf{k}) = \pm \omega(\mathbf{k}, m) \chi^{(D)\pm}(\mathbf{k}). \quad (1.11)$$

Equation (1.10) in turn follows⁹ from the fact that one

⁹ The proof is a simple extension of that for the case $\chi_1^{(D)\pm} = \chi_2^{(D)\pm}$ as given, for example, in S. S. Schweber, *An Introduction to Relativistic Quantum Field Theory* (Row Peterson & Company, New York, 1961), Chap. 4, preceding equation (129).

has, from (1.1) and (1.6),

$$(\gamma_\mu k^\mu - m) \chi_{1,2}^{(D)\pm} = 0. \quad (1.12)$$

In BC we considered momentum-dependent matrix transformations of the form

$$\psi^{(D)}(x) \rightarrow \psi'(x) = V(p, m) \psi^{(D)}(x), \quad (1.13)$$

leading to the equation

$$V(p, m) [\gamma_\mu p^\mu - m] V^{-1}(p, m) \psi' = 0. \quad (1.14)$$

Five special classes of such transformations were presented, with every transformation in a given class having two properties characteristic of that class.

The first of these properties is that the linearity in a corresponding one of the five quantities p_μ , m is maintained in the transformed equation. In this way “ p_0 -, “ p_1 -, “ p_2 -, “ p_3 -, and “ m -linear” equations are obtained.

Amongst the “ p_0 -linear” forms, one finds the Foldy-Wouthuysen-Tani¹⁰ equation

$$p_0 \psi^{(F)} = \gamma_0 \omega(\mathbf{p}, m) \psi^{(F)}, \quad (1.15)$$

with, in this case,

$$\psi^{(F)}(x) = F(\mathbf{p}, m) \psi^{(D)}(x), \quad (1.16)$$

where

$$F(\mathbf{p}, m) = \exp \left[\frac{\mathbf{Y} \cdot \mathbf{P}}{2 |\mathbf{p}|} \arctan \left(\frac{|\mathbf{p}|}{m} \right) \right]. \quad (1.17)$$

Also of the “ p_0 -linear” type is the equation proposed by Mendlowitz¹¹:

$$p_0 \psi^{(M)} = \omega(\mathbf{p}, m) \gamma_0 \frac{\mathbf{Y} \cdot \mathbf{P}}{|\mathbf{p}|} \psi^{(M)}, \quad (1.18)$$

where

$$\psi^{(M)}(x) = M(\mathbf{p}, m) \psi^{(D)}(x), \quad (1.19)$$

with

$$M(\mathbf{p}, m) = \exp \left[- \frac{\mathbf{Y} \cdot \mathbf{P}}{2 |\mathbf{p}|} \arctan \left(\frac{m}{|\mathbf{p}|} \right) \right]. \quad (1.20)$$

Amongst the “ m -linear” equations is that proposed by Chakrabarti¹²:

$$\epsilon(p_0) (p_\mu p^\mu)^{\frac{1}{2}} \gamma_0 \psi^{(C)} = m \psi^{(C)}, \quad (1.21)$$

where

$$\epsilon(p_0) = p_0 |p_0|^{-1} \quad (1.22)$$

and

$$\psi^{(C)}(x) = C(p) \psi^{(D)}(x), \quad (1.23)$$

¹⁰ L. L. Foldy and S. A. Wouthuysen, *Phys. Rev.* **78**, 29 (1950); S. Tani, *Progr. Theoret. Phys. (Kyoto)* **6**, 267 (1951). The transformation was in fact earlier proposed by M. H. L. Pryce, *Proc. Roy. Soc. (London)* **195A**, 62 (1948).

¹¹ H. Mendlowitz, *Phys. Rev.* **102**, 527 (1956). The transformation was rediscovered by M. Cini and B. Touschek, *Nuovo Cimento* **7**, 422 (1958); and independently by S. K. Bose, A. Gamba, and E. C. G. Sudarshan, *Phys. Rev.* **113**, 1661 (1959).

¹² A. Chakrabarti, *J. Math. Phys.* **4**, 1215, 1223 (1963).

with

$$C(p) = \exp \left\{ -\frac{\epsilon(p_0)\gamma_0\boldsymbol{\gamma} \cdot \mathbf{p}}{2|p|} \operatorname{arc\,tanh} \left(\frac{|p|}{|p_0|} \right) \right\}. \quad (1.24)$$

The simplest “ p_3 -linear” form obtained is

$$p_3\psi' = \epsilon(p_0)\lambda(p_0, p_1, p_2, m)\gamma_0\gamma_3\psi', \quad (1.25)$$

where

$$\lambda(p_0, p_1, p_2, m) = [(p_0)^2 - (p_1)^2 - (p_2)^2 - m^2]^{\frac{1}{2}} \quad (1.26)$$

and

$$\psi'(x) = W(p_0, p_1, p_2, m)\psi^{(D)}(x), \quad (1.27)$$

with

$$\begin{aligned} W(p_0, p_1, p_2, m) &= \exp \left\{ -\frac{\epsilon(p_0)\gamma_0(\gamma_1p_1 + \gamma_2p_2 + m)}{2[(p_1)^2 + (p_2)^2 + m^2]^{\frac{1}{2}}} \right. \\ &\quad \left. \times \operatorname{arc\,tanh} \left(\frac{[(p_1)^2 + (p_2)^2 + m^2]^{\frac{1}{2}}}{|p_0|} \right) \right\}. \end{aligned} \quad (1.28)$$

The second property characterizing a given one of the five classes is that every transformation within that class preserves the Dirac scalar product in a corresponding one of the five modes (1.8a)–(1.8c), so that each class consists of canonical transformations. In fact, the transformations leading to “ p_0 -, “ m -, and “ p_i -linear” forms preserve the modes (1.8a)–(1.8c), respectively.

In describing a subset of transformations (1.13) as momentum-dependent $SO(4, 1)$ transformations, making use of the connection between Eq. (1.1) and this group, we aim here in particular to interpret the above results of BC in group-theoretical terms. To this end, in Sec. 2, we make explicit this connection to the extent required in what follows.

In Sec. 3, the significance of such a connection in regard to transformations of the form (1.13) is established. We stress in particular the existence of five subgroups of $SO(4, 1)$, labeled by us $G^{(\alpha)}$ ($\alpha = 0, 1, 2, 3, 4$), which have the special property that any momentum-dependent transformation (1.13) within a given $G^{(\alpha)}$ leaves the equation linear in the corresponding p_α (where we write $p_4 = m$).

As might be expected, the five classes of canonical transformations presented in BC fall into these five subgroups and, in fact, every transformation in a given $G^{(\alpha)}$ also preserves the corresponding mode of the scalar product. This we show in Secs. 4, 5, and 6, where the subgroups $G^{(0)}$, $G^{(4)}$, and $G^{(3)}$ (as typical of $G^{(i)}$, $i = 1, 2, 3$) and, correspondingly, “ p_0 -, “ m -, and “ p_3 -linear” forms of the equation, are discussed in more detail. [It is not shown that an arbitrary momen-

tum-dependent $SO(4, 1)$ transformation is canonical—in fact it is not possible to write the scalar product (1.8a)–(1.8c) in $SO(4, 1)$ -invariant form.]

We find that $G^{(0)}$ is the maximal compact subgroup $SO(4)$, and $G^{(4)}$ the $SO(3, 1)$ group relating to the Lorentz transformation properties of the equation. The $G^{(i)}$ are also $SO(3, 1)$ subgroups, distinct from $G^{(4)}$ and from one another.

In Sec. 7, a discussion is given of the “little group” of $SO(4, 1)$ transformations which leave a particular transform of the equation invariant, and the nature of ambiguities which arise when one wishes to transform one equation into another are made explicit.

2. DIRAC EQUATION AND $SO(4, 1)$

The sixteen elements

$$I, \gamma_\mu, \gamma_5, \gamma_5\gamma_\mu, \text{ and } [\gamma_\mu, \gamma_\nu] \quad (2.1)$$

of the Dirac-Clifford algebra form a complete set of 4×4 matrices, in terms of which the infinitesimal generators of a four-dimensional representation of any Lie group can be expressed as linear combinations with complex coefficients.

In this connection, one is familiar with the case of $SO(3, 1)$,¹³ where the generators are defined as

$$S_{\mu\nu} = (i/4)[\gamma_\mu, \gamma_\nu] \quad (2.2)$$

and satisfy the characteristic Lorentz-group commutation rules

$$\begin{aligned} [S_{\mu\nu}, S_{\rho\sigma}] = & -i(g_{\mu\rho}S_{\nu\sigma} + g_{\nu\sigma}S_{\mu\rho} \\ & - g_{\mu\sigma}S_{\nu\rho} - g_{\nu\rho}S_{\mu\sigma}). \end{aligned} \quad (2.3)$$

The significance of these operators in regard to the Dirac equation is well known. In essence, the invariance of the Dirac description of free spin- $\frac{1}{2}$ particles under restricted homogeneous Lorentz transformations is expressed in the fact that

$$[\gamma_\mu p^\mu, J_{\rho\sigma}] = 0, \quad (2.4)$$

where

$$J_{\mu\nu} = L_{\mu\nu} + S_{\mu\nu} \quad (2.5)$$

and the $L_{\mu\nu}$, satisfying commutation rules analogous to (2.3), are defined by

$$L_{\mu\nu} = x_\mu p_\nu - x_\nu p_\mu. \quad (2.6)$$

Although not always referred to as such explicitly, representations of the Lie algebras of larger groups, such as $SO(4, 1)$ and $SO(4, 2)$, have been given in terms of (2.1) by, for example, Eddington,¹ Dirac,²

¹³ We have taken some license with notation in referring to the groups $SO(3, 1)$, $SO(4)$, and $SO(4, 1)$, when in fact the covering groups $SL(2, C)$, $SU(2) \otimes SU(2)$, etc., are meant.

Harish-Chandra,³ and Barut.⁴ The connection between the orthogonal groups in five dimensions [such as $SO(4, 1)$] and a class of relativistic wave equations, of which the Dirac equation is the simplest, was first discussed in detail by Lubański.⁵ More recently $S\tilde{U}(4)$ [of which $SO(4, 2)$ may be regarded as a type] has received attention from several authors⁶; and Barut,⁷ in particular, has exploited the connection between Eq. (1.1) and $SO(4, 2)$ in “reformulating the Dirac theory of the electron.”

For our purposes here it will be sufficient to indicate and use the relationship of the group $SO(4, 1)$ to the Dirac equation. Multiplying (1.1) by γ_5 , one obtains

$$(\gamma_5 \gamma_\mu p^\mu - \gamma_5 m) \psi^{(D)} = 0. \tag{2.7}$$

Defining

$$\Gamma_\mu = \gamma_5 \gamma_\mu, \quad \Gamma_4 = \gamma_5, \tag{2.8}$$

and

$$p^4 = -m, \tag{2.9}$$

one can write (2.7) as

$$\Gamma_\alpha p^\alpha \psi^{(D)} = 0, \tag{2.10}$$

where the summation is now over $\alpha = 0, 1, 2, 3$, and 4. In the following, note that indices take these values:

$$\begin{aligned} \alpha, \beta, \gamma, \delta, \epsilon: & 0, 1, 2, 3, 4, \\ \mu, \nu, \rho, \sigma: & 0, 1, 2, 3, \\ \tau, \zeta, \eta: & 0, 1, 2, 4, \\ a, b, c: & 1, 2, 3, 4, \\ i, j, k: & 1, 2, 3. \end{aligned}$$

Introducing $g^{\alpha\beta}$ ($= g_{\alpha\beta}$), with

$$\begin{aligned} g_{00} = -g_{11} = -g_{22} = -g_{33} = -g_{44} &= 1, \\ g_{\alpha\beta} &= 0, \quad \alpha \neq \beta, \end{aligned} \tag{2.11}$$

we define $\Gamma^\alpha = g^{\alpha\beta} \Gamma_\beta$, etc. Now defining also

$$T_{\alpha\beta} = (i/4)[\Gamma_\alpha, \Gamma_\beta] \tag{2.12}$$

and noting

$$\{\Gamma_\alpha, \Gamma_\beta\} = 2g_{\alpha\beta}, \tag{2.13}$$

we find

$$\begin{aligned} [T_{\alpha\beta}, T_{\gamma\delta}] = -i(g_{\alpha\gamma} T_{\beta\delta} + g_{\beta\delta} T_{\alpha\gamma} \\ - g_{\alpha\delta} T_{\beta\gamma} - g_{\beta\gamma} T_{\alpha\delta}), \end{aligned} \tag{2.14}$$

which are the characteristic commutation rules for the Lie algebra of $SO(4, 1)$. Since this group is non-compact, the $T_{\alpha\beta}$ are not all Hermitian, but

$$\Gamma_0 T_{\alpha\beta}^\dagger = T_{\alpha\beta} \Gamma_0. \tag{2.15}$$

One also has

$$[\Gamma_\alpha, T_{\beta\gamma}] = i(g_{\alpha\beta} \Gamma_\gamma - g_{\alpha\gamma} \Gamma_\beta). \tag{2.16}$$

Note that the ten different $T_{\alpha\beta}$ consist of the six different $T_{\mu\nu}$ [$\equiv S_{\mu\nu}$ of (2.2)] and four $T_{4\mu}$ [$= -(i/2)\gamma_\mu$], so that this Lie algebra is as small as any containing scalar multiples of all four Dirac matrices γ_μ .⁴ The representation of $SO(4, 1)$ generated by these ten operators is irreducible. The Casimir operators¹⁴ $-\frac{1}{2}T_{\alpha\beta}T^{\alpha\beta}$ and $-\omega_\alpha\omega^\alpha$, where

$$\omega_\alpha = \frac{1}{8}\epsilon_{\alpha\beta\gamma\delta\epsilon} T^{\beta\gamma} T^{\delta\epsilon} \tag{2.17}$$

($= \frac{3}{4}\Gamma_\alpha$ in this case), are multiples of the unit matrix by $-\frac{5}{2}$ and $-\frac{4}{1}\frac{5}{6}$, respectively.

It is worth mentioning that there are two inequivalent irreducible representations of the Clifford algebra defined by (2.13), both of four dimensions. By making the choice (2.8) for Γ_α , we fix on one of these. The other representation is obtained if one chooses instead

$$\Gamma_\mu = \gamma_5 \gamma_\mu, \quad \Gamma_4 = -\gamma_5 \tag{2.18}$$

(and so necessarily $p^4 = m$). The set of $T_{\alpha\beta}$ one obtains in this case is then also different, again with

$$T_{\mu\nu} = (i/4)[\gamma_\mu, \gamma_\nu], \tag{2.19}$$

but now

$$T_{4\mu} = +(i/2)\gamma_\mu. \tag{2.20}$$

However, these $T_{\alpha\beta}$ generate an *equivalent* representation of $SO(4, 1)$. (The invariants take the same values.) This is clear from the fact that this second set of $T_{\alpha\beta}$ is obtained from the first set via the substitution $\gamma_\mu \rightarrow -\gamma_\mu$. However, this can be achieved by a similarity transformation, because, under this substitution, a different set of matrices satisfying (1.3) is obtained and, as is well known, all irreducible representations of the Dirac-Clifford algebra are equivalent.

3. $SO(4, 1)$ TRANSFORMATIONS OF THE EQUATION

When written in the form (2.10), the Dirac equation has an $SO(4, 1)$ -invariant appearance. One might hope to find operators $M_{\beta\gamma}$ satisfying commutation rules analogous to (2.14), and such that \tilde{p} transforms¹⁵ as a five-vector operator with respect to transformations generated by them, that is, such that [cf. (2.16)]

$$[p_\alpha, M_{\beta\gamma}] = i(g_{\alpha\beta} p_\gamma - g_{\alpha\gamma} p_\beta). \tag{3.1}$$

One would then have, ensuring $SO(4, 1)$ invariance,

$$[\Gamma_\alpha p^\alpha, K_{\beta\gamma}] = 0, \tag{3.2}$$

¹⁴ See, for example, T. D. Newton, *Ann. Math.* **51**, 730 (1950).
¹⁵ We introduce at this point the notation \tilde{p} for the object with components p_α , distinguishing it from the four- and three-vector operators p and \mathbf{p} , respectively.

with

$$K_{\beta\gamma} = M_{\beta\gamma} + T_{\beta\gamma}; \tag{3.3}$$

however, such $M^{\beta\gamma}$ (and $K^{\beta\gamma}$) cannot be found, as is clear from (3.1) and the fact that p_4 is a constant. Nevertheless, one can consider the effect of transformations generated by all ten $T_{\beta\gamma}$ on the equation. Furthermore, despite the above conclusions, we shall see that it is in some ways convenient to regard \tilde{p} as a five-vector quantity and, similarly,

$$p_\alpha p^\alpha \equiv (p_0)^2 - (p_1)^2 - (p_2)^2 - (p_3)^2 - m^2 \tag{3.4}$$

as an $SO(4, 1)$ scalar.

Consider the $SO(4, 1)$ transformation

$$\Gamma_\alpha \rightarrow \Gamma'_\alpha = L^\beta_\alpha \Gamma_\beta [= (L\Gamma)_\alpha], \tag{3.5}$$

where L^β_α are real and satisfy

$$L^\beta_\alpha g^{\alpha\gamma} L^\delta_\gamma = g^{\beta\delta}, \tag{3.6}$$

$$L^0_0 \geq 1, \tag{3.7}$$

and

$$\det L = 1. \tag{3.8}$$

Then one can write

$$\Gamma'_\alpha = Q \Gamma_\alpha Q^{-1}, \tag{3.9}$$

where

$$Q = \exp [(i/2)\omega^{\alpha\beta} T_{\alpha\beta}], \tag{3.10}$$

with the $\omega^{\alpha\beta}$ ($= -\omega^{\beta\alpha}$) real quantities determined by the L^δ_γ . [The converse result also holds: (3.9) and (3.10) \Rightarrow (3.5)–(3.8).] Defining

$$\psi'(x) = Q \psi^{(D)}(x), \tag{3.11}$$

one obtains from (2.10) and (3.9) the equation

$$(L\Gamma)_\alpha p^\alpha \psi' = 0 \tag{3.12}$$

or, equivalently [using (3.6)],

$$\Gamma_\alpha (L^{-1}\tilde{p})^\alpha \psi' = 0. \tag{3.12'}$$

Thus this transformed equation is obtained from (2.10) by replacing therein the “five-vector” \tilde{p} with its transform under the $SO(4, 1)$ transformation inverse to the L of (3.5) [at the same time replacing $\psi^{(D)}$ by ψ' as in (3.11)]. Conversely, if \tilde{p}' is obtained from \tilde{p} by some arbitrary $SO(4, 1)$ transformation, then the equation

$$\Gamma_\alpha \tilde{p}'^\alpha \psi' = 0 \tag{3.13}$$

can be obtained from (2.10) by defining ψ' as in (3.11) with appropriate coefficients $\omega^{\alpha\beta}$ determining Q . Furthermore, since the p_α behave like real numbers to the extent that they commute with one another and with all Γ_β , and have only real eigenvalues on the

functions under consideration, a generalization to allow $\omega^{\alpha\beta}$ to be (Hermitian) functions of \tilde{p} is possible.

To summarize: The possible forms (3.13) of Dirac’s equation, obtained from (2.10) via transformations of the form (3.11), with $\omega^{\alpha\beta} = \omega^{\alpha\beta}(\tilde{p})$, are determined by the possible transforms \tilde{p}' of \tilde{p} ,

$$p'_\alpha = L^\beta_\alpha p_\beta, \tag{3.14}$$

where L^β_α are (Hermitian) functions of \tilde{p} satisfying (3.6–3.8). For all such transformations,

$$p'_\alpha p'^\alpha = p_\alpha p^\alpha \equiv p_\mu p^\mu - m^2, \tag{3.15}$$

and

$$\epsilon(p'_0) = \epsilon(p_0). \tag{3.16}$$

At this point we note that knowledge of \tilde{p}' is not sufficient to uniquely determine the transformation L^β_α of (3.14), as for any \tilde{p}' there is a “little group” of such transformations which leave it invariant. Correspondingly, there are transformations of the form (3.10), which, on application to a solution of a given equation (3.13), produce a further solution of the same equation. A further discussion of these questions is given in Sec. 7.

As mentioned in the Introduction, there are five subgroups, which we label $G^{(\alpha)}$, of $SO(4, 1)$, having particular significance when the question is raised of the canonicity of transformations of the form (3.11). $G^{(\alpha)}$ is that subgroup consisting of all $SO(4, 1)$ transformations which leave invariant arbitrary five-vectors whose only nonzero component is the α th. Since every component of the “five-vector” \tilde{p} appears linearly in (2.10), it follows that if \tilde{p}' is obtained from \tilde{p} by an $SO(4, 1)$ transformation (3.14) in $G^{(\beta)}$, the β component of \tilde{p} appears linearly also in (3.13), which we then refer to as “a ‘ p_β -linear’ form of the Dirac equation.”

4. $G^{(0)}$ AND “ p_0 -LINEAR” FORMS

The subgroup $G^{(0)}$ [the maximal compact subgroup $SO(4)$] acts only on the indices 1, 2, 3, and 4. The corresponding generators are T_{ab} , which are Hermitian matrices, and they in fact generate two inequivalent unitary irreducible representations of $SO(4)$, labeled by the two eigenvalues ± 1 of Γ_0 ($= \gamma_5 \gamma_0$), which is effectively a Casimir operator for this subgroup. (Note $[\Gamma_0, T_{ab}] = 0$.) Under the associated transformations (3.14), p_0 and $p_\alpha p^\alpha$ [$= -\omega^2(\mathbf{p}, m)$] remain separately invariant.

Thus, from

$$\tilde{p} = (p_0, p_1, p_2, p_3, m) \tag{4.1}$$

via $G^{(0)}$ transformations, one can obtain

$$\tilde{p}' = (p_0, p'_1, p'_2, p'_3, p'_4), \tag{4.2}$$

where the $p'_a(p_b)$ are Hermitian and

$$p'_a p'^a = -\omega^2(\mathbf{p}, m). \tag{4.3}$$

The corresponding equation (3.13) is in each case

$$(\Gamma_0 p^0 + \Gamma_a p'^a)\psi' = 0, \tag{4.4}$$

which gives, on multiplication with Γ_0 , the general “ p_0 -linear” form

$$p_0 \psi' = \gamma_0(\gamma_1 p'_1 + \gamma_2 p'_2 + \gamma_3 p'_3 + p'_4)\psi'. \tag{4.4'}$$

In considering the canonicity of momentum-dependent transformations in $G^{(0)}$, we note that when

$$\psi^{(D)}(x) \rightarrow Q(p, m)\psi^{(D)}(x), \tag{4.5}$$

where $Q(p, m)$ is as in (3.10) [with $\omega^{\alpha\beta} = \omega^{\alpha\beta}(\tilde{p})$], one has, from (1.6),

$$\chi^{(D)\pm}(\mathbf{k}) \rightarrow Q(k, m)\chi^{(D)\pm}(\mathbf{k}). \tag{4.6}$$

Furthermore, when in particular Q is in $G^{(0)}$, it follows from the Hermiticity of T_{ab} that $Q(k, m)$ is a unitary matrix. Every such transformation is therefore canonical, preserving the scalar product in the mode (1.8a).

All transformations presented in BC and yielding “ p_0 -linear” forms are of $G^{(0)}$ type. For example, in the simple cases of the Foldy–Wouthuysen–Tani equation, which corresponds to

$$\tilde{p}' = (p_0, 0, 0, 0, \omega(\mathbf{p}, m)), \tag{4.7}$$

and the Mendlowitz equation, which corresponds to

$$\tilde{p} = \left(p_0, \frac{\omega(\mathbf{p}, m)}{|\mathbf{p}|} p_1, \frac{\omega(\mathbf{p}, m)}{|\mathbf{p}|} p_2, \frac{\omega(\mathbf{p}, m)}{|\mathbf{p}|} p_3, 0 \right), \tag{4.8}$$

one sees that the corresponding transformations (1.17), (1.20) are indeed of the form

$$\exp [(i/2)\omega^{ab}T_{ab}], \tag{4.9}$$

with the ω^{ab} [= $\omega^{ab}(p_c)$] Hermitian. They are, in fact, the $SO(4, 1)$ transformations (3.10) corresponding to the “little group rotation-free” (l.g.r.f.) transformations $\tilde{p} \rightarrow \tilde{p}'$ in the two cases. More generally, corresponding to

$$\tilde{p}' = (p_0, \pm r q_1, \pm r q_2, \pm r q_3, \pm r q_4), \tag{4.10}$$

where the $q_a(p_b)$ are Hermitian,

$$r = \omega(\mathbf{p}, m)[-q_a q^a]^{-\frac{1}{2}}, \tag{4.11}$$

and

$$q_a(p^a - q^a) = 0, \tag{4.12}$$

from (4.4') one has

$$p_0 \psi' = \pm \omega(\mathbf{p}, m)[-q_a q^a]^{-\frac{1}{2}} \gamma_0(\gamma_1 q_1 + \gamma_2 q_2 + \gamma_3 q_3 + q_4)\psi', \tag{4.13}$$

which is the general “ p_0 -linear” form obtained in BC. [There are the \tilde{p}' as in (4.2) which cannot be expressed in the manner of (4.10)–(4.12), viz., those for which $p'_a p^a = 0$. The corresponding transformations and equations were not obtained in BC.] Again, the transformation presented in BC and yielding (4.13) corresponds to the l.g.r.f. transformation of \tilde{p} into \tilde{p}' as in (4.10).

The angles appearing in (1.17) and (1.20) can be regarded as those between the Euclidean “four vectors” p_a and p'_a through which one rotates to obtain p'_a in each case. [The idea of looking upon the Foldy–Wouthuysen–Tani and Mendlowitz transformations as rotations is not new,¹⁶ nor is the use of the group $G^{(0)}$ in discussing them: it is evident in the work of Bollini and Giambiagi,¹⁷ who have not, however, noted the connection with $SO(4, 1)$.]

5. $G^{(4)}$ AND “ m -LINEAR” FORMS

$G^{(4)}$ is the $SO(3, 1)$ group associated with homogeneous Lorentz transformations. Thus momentum-dependent $SO(4, 1)$ transformations (3.14) in $G^{(4)}$ leave $p_4 (= m)$, $p_\mu p^\mu$, and also $\epsilon(p_0)$ separately invariant. The associated generators $T_{\mu\nu}$ are not all Hermitian, but satisfy

$$T_{\mu\nu}^\dagger = \Gamma_0 \Gamma_4 T_{\mu\nu} \Gamma_0 \Gamma_4 (= \gamma_0 T_{\mu\nu} \gamma_0) \tag{5.1}$$

and, as is well known, they generate two inequivalent irreducible representations of $SO(3, 1)$, labeled by the two eigenvalues $\pm i$ of $\Gamma_4 (= \gamma_5)$ (cf. the case of $G^{(0)}$).

From

$$\tilde{p} = (p_0, p_1, p_2, p_3, m), \tag{5.2}$$

via $G^{(4)}$ transformations, one can obtain

$$\tilde{p}' = (p'_0, p'_1, p'_2, p'_3, m), \tag{5.3}$$

where the $p'_\mu(p_\nu)$ are Hermitian,

$$p'_\mu p'^\mu = p_\nu p^\nu, \tag{5.4}$$

and

$$\epsilon(p'_0) = \epsilon(p_0). \tag{5.5}$$

In each case, Eq. (3.13) is

$$(\Gamma_\mu p'^\mu - \Gamma_4 m)\psi' = 0, \tag{5.6}$$

yielding the general “ m -linear” form

$$m\psi' = \gamma_\mu p'^\mu \psi'. \tag{5.6'}$$

It should be mentioned at this point that, because of the way it is obtained, p'_μ will not, in general,

¹⁶ See, for example, K. M. Case, Phys. Rev. **95**, 1323 (1954).
¹⁷ C. G. Bollini and J. J. Giambiagi, Nuovo Cimento **21**, 107 (1961). See also Ref. 19. Note added in proof: Since the preparation of this paper, E. de Vries [Physica **43**, 45 (1969)] has independently established this connection.

be a Lorentz four-vector operator like p_μ . Our notation is perhaps misleading in this regard: \tilde{p} is better regarded as a numerical five-vector than a five-vector operator for the purposes of this paper.

Each momentum-dependent transformation in $G^{(4)}$ is also canonical. This follows from the fact that (5.1) implies that the corresponding $Q(k, m)$ of (4.6) satisfies

$$Q^{-1}(k, m) = \gamma_0 Q^\dagger(k, m) \gamma_0, \tag{5.7}$$

so that the scalar product in the mode (1.8b) is preserved in every case.

Every transformation presented in BC and leading to an “ m -linear” equation is of $G^{(4)}$ type (again corresponding to the l.g.r.f. transformation of \tilde{p} into \tilde{p}' in each case). Thus, for example, in the Chakrabarti case, where

$$\tilde{p}' = (\epsilon(p_0)(p_\mu p^\mu)^{\frac{1}{2}}, 0, 0, 0, m), \tag{5.8}$$

the l.g.r.f. transformation (1.24) is indeed of the form

$$\exp \{ (i/2) \omega^{\mu\nu} T_{\mu\nu} \}. \tag{5.9}$$

In fact, all \tilde{p}' of the form (5.3) can be written as

$$\tilde{p}' = (rq_0, rq_1, rq_2, rq_3, m), \tag{5.10}$$

with $q_\mu(p_\nu)$ Hermitian, $q_\mu q^\mu$ positive-definite,

$$r = (p_\mu p^\mu)^{\frac{1}{2}} (q_\nu q^\nu)^{-\frac{1}{2}}, \tag{5.11}$$

and

$$q_\mu (p^\mu - q^\mu) = 0. \tag{5.12}$$

[Proof: Take $q_\rho = p'_\mu p^\mu (p_\nu p^\nu)^{-1} p'_\rho$, noting that $p'_\mu p^\mu$ is positive-definite because of (5.5).] Then (5.6') becomes

$$m\psi' = (p_\mu p^\mu)^{\frac{1}{2}} (q_\nu q^\nu)^{-\frac{1}{2}} \gamma_\rho q^\rho \psi', \tag{5.13}$$

which is the general “ m -linear” form presented in BC.

Whereas in the case of the compact subgroup $G^{(0)}$ one can talk of an “angle of rotation” for each transformation, here one typically has pseudoangles associated with the anti-Hermitian T_{0i} , generators of “boosts” rather than rotations [cf. (1.24)].

6. $G^{(3)}$ AND “ p_3 -LINEAR” FORMS

Each of the three subgroups $G^{(i)}$ is again an $SO(3, 1)$ group. Transformations of the form (3.14) within $G^{(3)}$ leave $p_3, p_r p^r$, and $\epsilon(p_0)$ separately invariant. The corresponding generators $T_{r\eta}$ in this case are not all Hermitian, but

$$T_{r\eta}^\dagger = \Gamma_0 \Gamma_3 T_{r\eta} \Gamma_0 \Gamma_3 (= \gamma_0 \gamma_3 T_{r\eta} \gamma_0 \gamma_3). \tag{6.1}$$

In complete analogy with the case of $G^{(4)}$, the $T_{r\eta}$ generate two inequivalent irreducible representations of $SO(3, 1)$, labeled by the two eigenvalues $\pm i$ of $\Gamma_3 (= \gamma_3 \gamma_3)$ in this case.

From

$$\tilde{p} = (p_0, p_1, p_2, p_3, m), \tag{6.2}$$

via $G^{(3)}$ transformations, one can obtain

$$\tilde{p}' = (p'_0, p'_1, p'_2, p_3, p'_4), \tag{6.3}$$

where the $p'_r(p_\eta)$ are Hermitian,

$$p'_r p'^r = p_\eta p^\eta [= \lambda^2(p_0, p_1, p_2, m)], \tag{6.4}$$

and

$$\epsilon(p'_0) = \epsilon(p_0). \tag{6.5}$$

(Note that the transformations may become singular as $p_r p^r \rightarrow 0$.) The corresponding equation (3.13) in each case is

$$(\Gamma_r p'^r - \Gamma_3 p_3) \psi' = 0 \tag{6.6}$$

or, equivalently, the general “ p_3 -linear” form

$$p_3 \psi' = -\gamma_3 (\gamma_0 p'_0 - \gamma_1 p'_1 - \gamma_2 p'_2 - p'_4) \psi'. \tag{6.6'}$$

Again in analogy with the $G^{(4)}$ case, one finds that every momentum-dependent transformation in $G^{(3)}$ is canonical, the scalar-product mode [(1.8c); $i = 3$] being preserved in each case as a result of (6.1).

The transformations presented in BC and leading to “ p_3 -linear” equations are all of $G^{(3)}$ type (in each case corresponding to the l.g.r.f. transformation of \tilde{p} into \tilde{p}'). In the simplest case, for example, where the equation is (1.25), corresponding to

$$\tilde{p}' = (\epsilon(p_0)(p_r p^r)^{\frac{1}{2}}, 0, 0, p_3, 0), \tag{6.7}$$

the l.g.r.f. transformation (1.28) is indeed of the form

$$\exp \{ (i/2) \omega^{r\eta} T_{r\eta} \}. \tag{6.8}$$

Furthermore, all \tilde{p}' as in (6.3) can be written in the form

$$\tilde{p}' = (rq_0, rq_1, rq_2, p_3, rq_4), \tag{6.9}$$

where $q_r(p_\eta)$ are Hermitian, $q_r q^r$ is positive-definite,

$$r = (p_r p^r)^{\frac{1}{2}} (q_\eta q^\eta)^{-\frac{1}{2}}, \tag{6.10}$$

and

$$q_r (p^r - q^r) = 0. \tag{6.11}$$

[Take $q_\zeta = p'_r p^r (p_\eta p^\eta)^{-1} p'_\zeta$.] Equation (6.6') then becomes the general “ p_3 -linear” form of BC:

$$p_3 \psi' = -\lambda (p_0, p_1, p_2, m) (q_r q^r)^{-\frac{1}{2}} \times \gamma_3 (\gamma_0 q_0 - \gamma_1 q_1 - \gamma_2 q_2 - q_4) \psi'. \tag{6.12}$$

Again pseudoangles rather than angles appear in association with the anti-Hermitian generators T_{0r} [cf. (1.28)].

7. SIGNIFICANCE OF THE LITTLE GROUP

We have mentioned that for a given “five vector” \tilde{p}' there is a little group of $SO(4, 1)$ transformations which leave it invariant. We are dealing here only with functions on which $p'_\alpha p'^\alpha (= p_\alpha p^\alpha = p_\mu p^\mu - m^2)$ vanishes. In order to identify the little group appropriate in this situation, consider the particular case (corresponding to the Foldy–Wouthuysen–Tani equation)

$$\tilde{p}' = (p_0, 0, 0, 0, \omega(\mathbf{p}, m)). \tag{7.1}$$

It is seen that the matrix generators corresponding to the little group in this case are

$$T_{12}, T_{23}, \text{ and } T_{31}, \tag{7.2}$$

together with

$$T_{10} - \epsilon(p_0)T_{14}, \quad T_{20} - \epsilon(p_0)T_{24}, \tag{7.3}$$

$$\text{and } T_{30} - \epsilon(p_0)T_{34}.$$

The Lie algebra of (7.2) and (7.3) is isomorphic to that of the three-dimensional Euclidean group, (7.2) being the generators of “rotations,” and (7.3) of “translations.”

However, from (3.13) and (7.1), we find that $\Gamma_0 - \epsilon(p_0)\Gamma_4$ vanishes on the wavefunctions involved here. Multiplying this by $(i/2)\Gamma_j$ ($j = 1, 2, \text{ or } 3$), we obtain the result that this is also true of each of the generators (7.3). Thus the little group is effectively reduced to $SU(2)$.¹⁸

We conclude that, for any given \tilde{p}' , the little group consists of an effective part, which is $SU(2)$, and an ineffective part. Any transformation in the ineffective part is unity when applied to a wavefunction satisfying (3.13), while one in the effective part produces a new function satisfying the same equation. Note that \tilde{p}' , as in (7.1), can be obtained from \tilde{p} by a transformation in $G^{(0)}$ and that the effective little group generators in this case (7.2) also generate $G^{(0)}$ transformations. This indicates that if (3.13) is obtained from (2.10) by means of a canonical $SO(4, 1)$ transformation (i.e., a transformation in one of the subgroups $G^{(\alpha)}$), a subsequent little-group transformation leaving (3.13) invariant is also canonical.

It is clear that any \tilde{p}' and \tilde{p}'' obtained from \tilde{p} by $SO(4, 1)$ transformations (3.14) must themselves be linked by a further such transformation. Furthermore, by a procedure analogous to that used in obtaining (3.13) from (2.10), it is possible to obtain the equation

$$\Gamma_\alpha p''^\alpha \psi'' = 0 \tag{7.4}$$

¹⁸ There is a marked analogy here with the case of the little group (in the usual connection with the Poincaré group now) appropriate to a particle of zero rest mass and nonzero spin, as treated by V. Bargmann and E. P. Wigner, Proc. Natl. Acad. Sci. U.S. **34**, 211 (1948). See also de Vos and Hilgevoord (Ref. 5) in this connection.

directly from

$$\Gamma_\alpha p'^\alpha \psi' = 0. \tag{7.5}$$

Denoting by Q'' and Q' the operators (3.10) used to obtain ψ'' and ψ' , respectively, from $\psi^{(D)}$, we have, trivially,

$$\psi'' = Q'' Q'^{-1} \psi'. \tag{7.6}$$

While the operator $Q'' Q'^{-1}$ certainly corresponds to an $SO(4, 1)$ transformation taking \tilde{p}' into \tilde{p}'' and enables one to obtain (7.4) from (7.5), it will not in general correspond to the l.g.r.f. such transformation, even if Q'' and Q' correspond to the l.g.r.f. transformations taking \tilde{p} into \tilde{p}'' , \tilde{p}' , respectively. More precisely, if we denote by $Q(\tilde{p}', \tilde{p})$, $Q(\tilde{p}'', \tilde{p})$, and $Q(\tilde{p}'', \tilde{p}')$ the operators (3.10) corresponding to the l.g.r.f. transformations taking \tilde{p} into \tilde{p}' , \tilde{p} into \tilde{p}'' , and \tilde{p}' into \tilde{p}'' , respectively, then in general

$$Q(\tilde{p}'', \tilde{p}') = \Lambda Q(\tilde{p}'', \tilde{p}) Q^{-1}(\tilde{p}', \tilde{p}), \tag{7.7}$$

where Λ is also of the form (3.10) and corresponds to an $SO(4, 1)$ transformation in the little group defined by \tilde{p}'' . If Λ is in the effective part of the little group, then $Q(\tilde{p}'', \tilde{p}')$ and $Q(\tilde{p}'', \tilde{p}) Q^{-1}(\tilde{p}', \tilde{p})$ will differ on the wavefunctions ψ' ; but if it is in the ineffective part, then these two operators, while perhaps differing formally, will produce the same result when applied to any such ψ' satisfying (7.5).

As an example, consider the case when \tilde{p}' is as in (7.1), and

$$\tilde{p}'' = (\epsilon(p_0)(p_\mu p^\mu)^{\frac{1}{2}}, 0, 0, 0, m), \tag{7.8}$$

corresponding to the Chakrabarti equation. It is seen that in this case the l.g.r.f. transformation taking \tilde{p}' into \tilde{p}'' is in the 0–4 plane, and correspondingly,

$$Q(\tilde{p}'', \tilde{p}') = \exp(i\varphi T_{04}) \tag{7.9}$$

$$= \cosh(\frac{1}{2}\varphi) - \gamma_0 \sinh(\frac{1}{2}\varphi), \tag{7.9'}$$

where $\varphi(\tilde{p})$ is Hermitian. A straightforward calculation of the pseudoangle φ involved in this “boost” transformation yields

$$\varphi(\tilde{p}) = \text{arc tanh} \{ \epsilon(p_0) [\mathcal{E}^2 - \mathcal{M}^2] [\mathcal{E}^2 + \mathcal{M}^2]^{-\frac{1}{2}} \}, \tag{7.10}$$

where

$$\mathcal{E} = \frac{1}{2} [|p_0| + \omega(\mathbf{p}, m)] \tag{7.11}$$

and

$$\mathcal{M} = \frac{1}{2} [(p_\mu p^\mu)^{\frac{1}{2}} + m]. \tag{7.12}$$

Then

$$\cosh(\frac{1}{2}\varphi) = \frac{1}{2} [[\mathcal{E}/\mathcal{M}]^{\frac{1}{2}} + [\mathcal{M}/\mathcal{E}]^{\frac{1}{2}}] \tag{7.13}$$

and

$$\sinh(\frac{1}{2}\varphi) = [\frac{1}{2} \epsilon(p_0)] \{ [\mathcal{E}/\mathcal{M}]^{\frac{1}{2}} - [\mathcal{M}/\mathcal{E}]^{\frac{1}{2}} \}. \tag{7.14}$$

Because \tilde{p}' in this case corresponds to the Foldy-Wouthuysen-Tani equation, Eq. (7.5) yields

$$\mathcal{M}\psi' = m\psi', \tag{7.15}$$

$$\varepsilon\psi' = \omega(\mathbf{p}, m)\psi', \tag{7.16}$$

and

$$\epsilon(p_0)\gamma_0\psi' = \psi'. \tag{7.17}$$

It follows then from (7.9') and (7.13)–(7.17) that

$$Q(\tilde{p}'', \tilde{p}')\psi' = [m/\omega(\mathbf{p}, m)]^{\frac{1}{2}}\psi'. \tag{7.18}$$

However, in this example we have

$$Q(\tilde{p}', \tilde{p}) \equiv F(\mathbf{p}, m) \tag{7.19}$$

and

$$Q(\tilde{p}'', \tilde{p}) \equiv C(p), \tag{7.20}$$

and it is known that¹⁹

$$\begin{aligned} \psi^{(C)}(x) & [= C(p)F^{-1}(\mathbf{p}, m)\psi^{(F)}(x)] \\ & = [m/\omega(\mathbf{p}, m)]^{\frac{1}{2}}\psi^{(F)}(x). \end{aligned} \tag{7.21}$$

Thus from (7.18) we deduce

$$Q(\tilde{p}'', \tilde{p}')\psi^{(F)} = C(p)F^{-1}(\mathbf{p}, m)\psi^{(F)} \tag{7.22}$$

$$= Q(\tilde{p}'', \tilde{p})Q^{-1}(\tilde{p}', \tilde{p})\psi^{(F)}. \tag{7.22'}$$

On inspection, however, $Q(\tilde{p}'', \tilde{p}')$ and $Q(\tilde{p}'', \tilde{p}) \times Q^{-1}(\tilde{p}', \tilde{p})$ are found to be formally distinct, and we conclude that they are related in the manner (7.7), with Λ in the ineffective part of the little group of \tilde{p}'' .

8. CONCLUSION

The connection between the group $SO(4, 1)$ and the free-particle Dirac equation can be exploited to allow the presentation of a unified treatment of the well-known canonical transformations of the equation. Similarities and relationships between these transformations assume a new and simple significance in such a treatment.

This approach also makes obvious the existence and also the actual form of many other similar canonical transformations, some of which we feel will prove

useful⁸ in discussing limiting situations other than the nonrelativistic and extreme-relativistic ones (where the Foldy-Wouthuysen-Tani and the Mendlowitz transformations, respectively, are most appropriate).

It is tempting to speculate as to a deeper physical significance of the group $SO(4, 1)$ itself in this context, in view of recent activity centering on this and related groups in connection with dynamical symmetries^{4,20} for elementary particles. However, there are relativistic wave equations, linear in the energy-momentum operators, for which there is no simple connection with $SO(4, 1)$.²¹ For all such equations describing massive particles, it is, however, a consequence of Lorentz invariance that there will be a Chakrabarti-type transformation corresponding to the transformation of the four momentum to the rest frame: Such a transformation expresses the canonical Wigner amplitudes in terms of the manifestly covariant ones.

Foldy and Wouthuysen¹⁰ generalized their approach to the free-particle Dirac equation to gain considerable insight into the problem of the Dirac particle in interaction with a weak electromagnetic field, and this approach has been pursued consequently by several authors.²² The Foldy-Wouthuysen method involves a perturbation procedure and yields a “ p_0 -linear” equation containing an infinite number of terms. In the absence of the interaction, this equation reduces to their form of the free-particle equation. One of us (H. A. C.) has generalized this procedure to develop similar expansions corresponding to various other forms obtainable from the free-particle Dirac equation via canonical $SO(4, 1)$ transformations.

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²⁰ See, for example, A. Böhm, *Phys. Rev.* **175**, 1767 (1968); C. Fronsdal, *Phys. Rev.* **156**, 1665 (1967); Y. Nambu, *Phys. Rev.* **160**, 1171 (1967); A. O. Barut, *Phys. Rev. Letters* **26B**, 308 (1968).

²¹ We are indebted to Professor C. A. Hurst for this information.

²² See E. Eriksen and M. Kolsrud, *Nuovo Cimento Suppl.* **18**, 1 (1960), and references therein.

¹⁹ R. H. Good, Jr., and M. E. Rose, *Nuovo Cimento* **24**, 864 (1962).